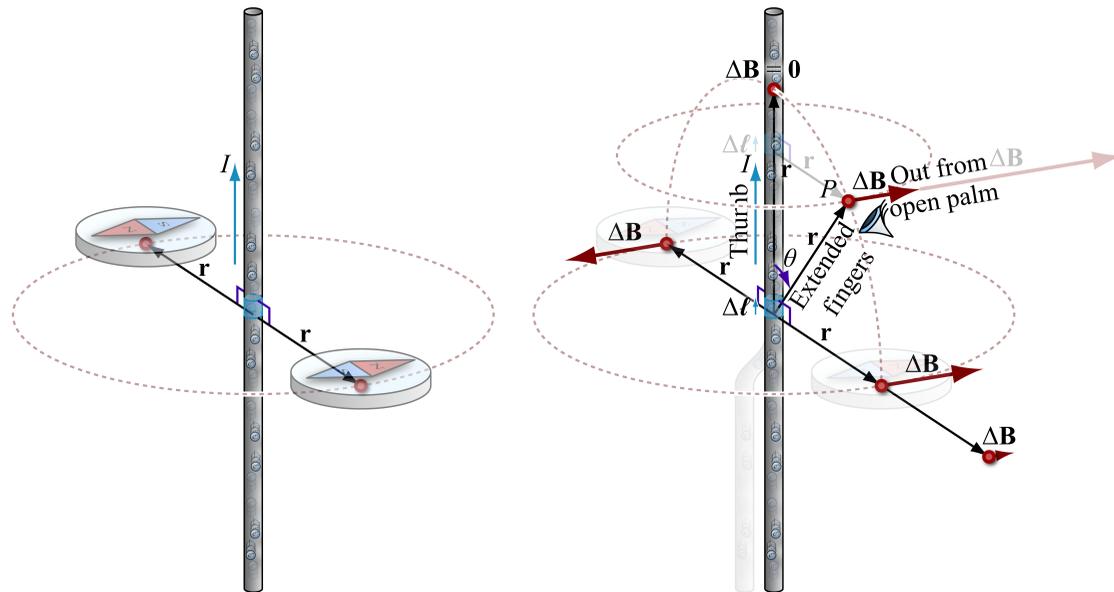


Magnetism (algebra-based physics)

Moving charges create magnetic fields, and magnetic fields exert magnetic forces on moving charges.

Motivating differential form of Biot-Savart law



$$\Delta \vec{B} = \frac{\mu_0 I \Delta \vec{\ell} \times \hat{r}}{4\pi r^2} = \frac{\mu_0 I |\Delta \vec{\ell}| \sin \theta}{4\pi r^2} \vec{u}_{\Delta \vec{\ell} \times \hat{r}}$$

[B] = T

$$\mu_0 = 4\pi \times 10^{-7} \frac{\text{T} \cdot \text{m}}{\text{A}}$$

(All panels illustrate right hand rules)

Superposition

$$\vec{B} = \sum \Delta \vec{B}$$

⊙ out (arrowhead)
⊗ in (fletching)

Steps for applying Biot-Savart law

Neatly and graphically represent situation(s)

1. Draw current distribution.
2. Draw observation point P.

Graphically represent quantities and their relationships

3. Draw macaroni $\Delta \vec{\ell}$.
4. Draw \vec{r} from macaroni to P.
5. Draw angle θ between macaroni $\Delta \vec{\ell}$ and \vec{r} .
6. Use RHR to find direction of cross product. Draw $\Delta \vec{B}$ in this direction.

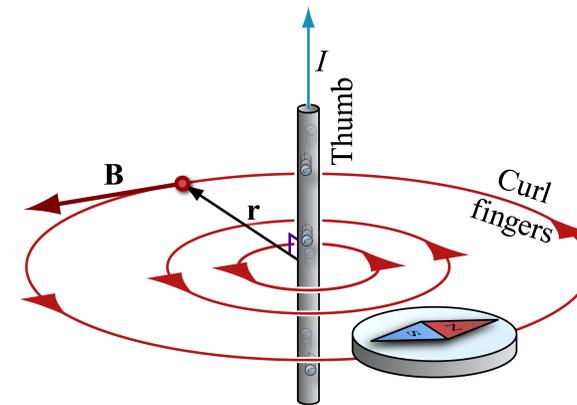
Identify relevant allowed starting point (in)equation(s)

Use numbered steps to show REASoNing

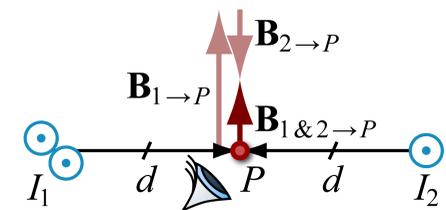
Communicate

Results

Steady infinite line current



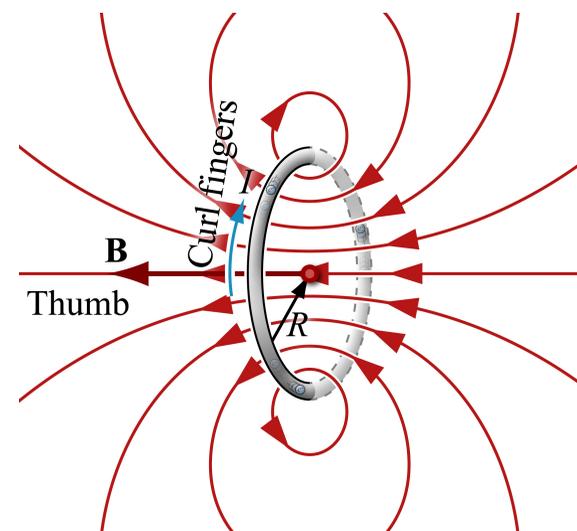
$$|\vec{B}| = \frac{\mu_0 I}{2\pi r}$$



Superposition

$$\vec{B}_{1\&2\&\dots\rightarrow P} = \vec{B}_{1\rightarrow P} + \vec{B}_{2\rightarrow P} + \dots$$

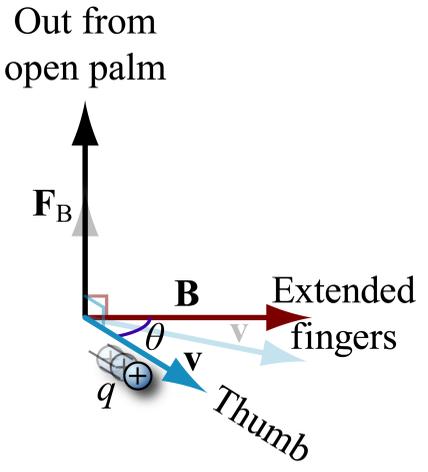
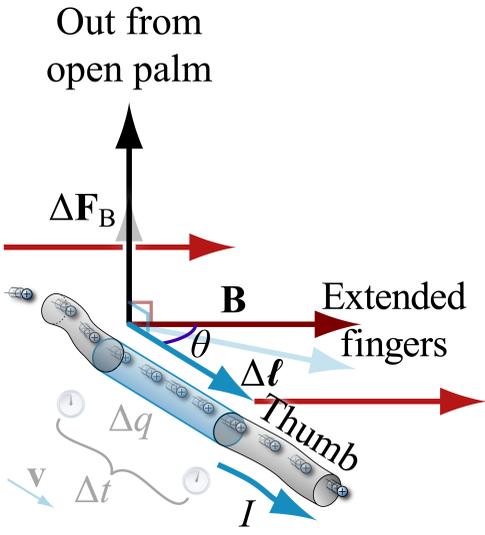
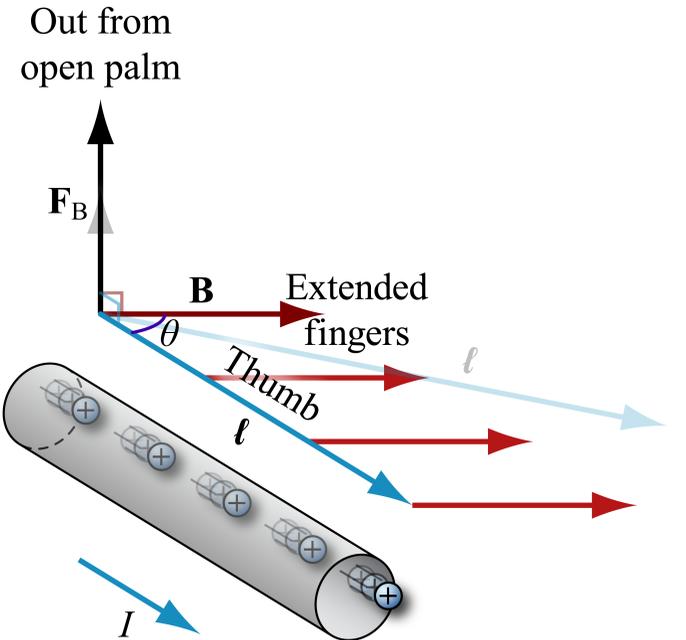
Steady circular loop current



$$|\vec{B}_{\text{CENTER}}| = \frac{\mu_0 I}{2R}$$

Magnetism (algebra-based physics)

Moving charges create magnetic fields, and **magnetic fields exert magnetic forces on moving charges.**

Magnetic force on a moving charge	Magnetic force on a very small current element	Magnetic force on a line segment of current
 <p>Out from open palm</p> <p>\vec{F}_B</p> <p>\vec{B} Extended fingers</p> <p>θ</p> <p>Thumb</p> <p>q</p> <p>\vec{v}</p> <p>(RHR for positive moving charge illustrated; for negative moving charge, reverse direction of thumb)</p>	 <p>Out from open palm</p> <p>$\Delta \vec{F}_B$</p> <p>\vec{B} Extended fingers</p> <p>θ</p> <p>Thumb</p> <p>$\Delta \vec{\ell}$</p> <p>I</p> <p>Δq</p> <p>Δt</p> <p>\vec{v}</p>	 <p>Out from open palm</p> <p>\vec{F}_B</p> <p>\vec{B} Extended fingers</p> <p>θ</p> <p>Thumb</p> <p>$\vec{\ell}$</p> <p>I</p>
$\vec{F}_B = q\vec{v} \times \vec{B}$ $ \vec{F}_B = q \vec{v} \sin \theta \vec{B} $	$\Delta \vec{F}_B = I \Delta \vec{\ell} \times \vec{B}$ $= I \Delta \vec{\ell} \vec{B} \sin \theta \vec{u}_{\Delta \vec{\ell} \times \vec{B}}$	$\vec{F}_B = I \vec{\ell} \times \vec{B}$ $ \vec{F}_B = I \vec{\ell} \sin \theta \vec{B} $
$\Delta \vec{F}_B = \Delta q \vec{v} \times \vec{B}$ $= \Delta q \frac{\Delta \vec{\ell}}{\Delta t} \times \vec{B}$ $= \frac{\Delta q}{\Delta t} \Delta \vec{\ell} \times \vec{B}$	<p>Steps for applying law for magnetic force on a very small current element</p> <hr/> <p>Neatly and graphically represent situation(s)</p> <ol style="list-style-type: none"> 1. Draw current distribution. <hr/> <p>Graphically represent quantities and their relationships</p> <ol style="list-style-type: none"> 2. Draw background \vec{B}-field. 3. Draw macaroni $\Delta \vec{\ell}$, local \vec{B}, and angle θ between $\Delta \vec{\ell}$ and local \vec{B}. 4. Use RHR to find direction of magnetic force on current element. Draw $\Delta \vec{F}_B$ in this direction. <hr/> <p>Identify relevant allowed starting point (in)equation(s)</p> <hr/> <p>Use numbered steps to show REASoNing</p> <hr/> <p>Communicate</p>	